



#### **Fusion-Enabled Pluto Orbiter and Lander**

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# **Outline of Talk**

- Electric propulsion
- Pluto mission overview
- Mission design
- Spacecraft design
- DFD overview and status
  - FRC with odd-parity RF heating
  - D  $^{3}$ He fuel
- DFD subsystems
- Work in progress and conclusions



Simulation of DFD Pluto Approach

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## **Electric Propulsion**



## **Specific Power**

- Plot on right based on work done assuming direct insertion
- Other electric propulsion systems
  - Solar not applicable to outer planet missions
  - Fission Electric





### **Destination: Pluto Orbit**



Put a spacecraft in orbit around Pluto, power a lander using optical transmission, return high-definition video – and get there in only **4 years**!



## **Pluto Mission**

- Deliver payload 1000 kg of orbiter and lander
- 1158 L of <sup>3</sup>He for the entire mission
- Arrives in just 4 years
- Provides 2 MW of electrical power
  - Beam 30 kW down to lander
- Launch mass can be accommodated by almost any launch vehicle
- <sup>3</sup>He fuel can be purchased in sufficient quantities now from available suppliers





## **Pluto Mission Comparison**

Parameter	New Horizons	DFD Mission
Travel time to Pluto	9.5 years	4 years
Delta-V	290 m/s	70,000 m/s
Power at Pluto	200 W	2,000,000 W
Data rate to Earth	1 kbit/s	> 1,000,000 kbit/s
Fuel	Plutonium	D- <sup>3</sup> He
Trajectory	Jupiter Swingby	Direct
Mission type	Flyby	Orbit
Lander	No	Yes

Bottom Line: You can't do the proposed mission to Pluto with any other technology.



## **Mission Outline**

- Earth departure
- Acceleration Coast Deceleration
  - Depends on available thrust
- Insertion into Pluto flyby orbit
- Orbit insertion
- Orbit operations
  - Lander deployment
  - Pluto observations
  - Lander power from orbit



## Spacecraft

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- Wide range of scientific instruments for Pluto orbit survey and a lander
- Large radiators for waste heat rejection
- Cylindrical structure is sun shade with MLI
- Optical communications for HDTV bandwidth to Earth
- Fully autonomous guidance, navigation and control

Comparison with Hubble Space Telescope





## Guidance, Navigation and Control (GN&C)





## GN&C

- Optical navigation used throughout
  - Reduces reliance on Deep Space Network
  - Provides continuous updates during burns
  - Operates in heliocentric or Pluto centric modes
- Reaction wheels for attitude control
- Steered plasma plumes for pitch and yaw momentum unloading and control during burns
- Attitude control thrusters for roll control and unloading



#### UKF is Unscented Kalman Filter



## **Departure from Earth**

#### • Two options

- Direct insertion into heliocentric trajectory
- Departure from LEO
- Direct insertion (rocket put: the vehicle directly into heliocentric orbit) requires Delta IV Heavy class launcher
  - \$350M launch cost
- Departure from low earth parking orbit
  - \$60M launch cost
  - Requires additional fuel
  - Allows for on-orbit checkout



Simulation of DFD Pluto Vehicle near ISS prior to departure



## **Departure Trajectory**

- Assume ISS orbit
  - Allows astronaut checkout prior to departure
- Burn along velocity vector
  - Not optimal
- 40 N thrust assumed
- Orbit becomes hyperbolic in 7.5 days
  - e is orbit eccentricity
  - > 1 is hyperbolic
- Major cost savings
- On-orbit checkout reduces mission risk





## Arrival at Pluto

- Optimal trajectory
  - Uses MATLAB's fmincon
    - Brute force direct method
    - There are other methods
  - Two dimensional problem
  - Inequality constraint on acceleration magnitude
  - Starts in flyby hyperbola
  - Uses twice the velocity change of an impulsive burn at closest approach





### Princeton Field Reversed Configuration (PFRC)

- RF heating with rotating magnetic fields naturally limits reactor size
  - Plasma radius in range 20-40 cm
  - Power of 1-10 MW is ideal for space
- Confinement with superconducting coils
- Ultra low radiation

- Linear configuration allows for configuration as a rocket engine
- Flow more D<sup>+</sup> to augment thrust
- Exit via magnetic nozzle
- Variable exhaust velocity
  - 50 to 20,000 km/s
  - $P = 0.5 Tu_e/\eta$ , thrust ~ 10-50 N





## Status of PFRC Development

- Princeton Plasma Physics Laboratory performing experiments with Dept. of Energy funding
  - Concluded PFRC-1 a, b, c in 2011
  - PFRC-2 operating now; goal to demonstrate keV plasmas with pulse lengths to 0.3 s
  - Computational studies on plasma detachment in nozzle
- Princeton Satellite Systems performing mission and trajectory design, space balance of plant studies under IR&D and now NIAC



-	Four	joint	PPPL,	/PSS	patents
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Machine	PFRC-1	PFRC-2	PFRC-3A	PFRC-3B
Objectives	Electron Heating	Ion Heating	Heating above 5 keV	D-He3 Fusion
Fuel	н	н	н	D-3He
Goals/ Achievements*	3 ms pulse* 0.15 kG field* e-temp = 0.3 keV*	0.1 s pulse* 1.2 kG field i-temp = 1 keV	10 s pulse 10 kG field i–temp = 5 keV	10 s pulse 80 kG field i-temp = 50 keV
Plasma Radius	4 cm	8 cm	16 cm	16 cm
Time Frame	2008-2011	2011-2017	2018-2022	2022-2026
Cost	\$2M	\$4M	\$25M	\$25M





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# Heat Recycling

- Brayton cycle heat engine
  - Heat high pressure gas to do work
- Used in High Temperature Gas Cooled Fission Reactors
- Helium working fluid
- Paired compressor/turbine sets with counter-rotating turbines and compressors
- Common shaft for compressor, turbine and generator
- Need for multiple compressor and turbine stages and recuperator to be determined
- Large radiator wings







## Superconducting Coils Designed for Space

- Alpha Magnetic Spectrometer-02
- Looking for anti-matter and dark matter
- Cooled with superfluid helium









## **Superconducting Coils**

- Eight discrete coils in a 4 m machine
  - Some ripple which would be reduced by the plasma field
- Axial field compatible with HTS and NbTi LTS
- Forces between coils are  $5.7 \times 10^6$  N







## **Power Generation and Distribution**

- Power generated by a 3 phase axialflux Halbach Generator
  - Distribution is 3 phase to RF drive
  - 98% efficient at design point
  - AC/DC converters and 3 phase to one phase converters as needed
- A very small Halbach motor/ generator developed at Princeton Satellite Systems for an Army satellite





Driver configured as motor



## **Radio-Frequency Heating**

- Odd-parity rotating magnetic field
- Class E power RF amplifiers
  - Transistor operates as on on/off switch
  - Load network shapes waveform so that the current and voltage do not simultaneously peak thus minimized power dissipation (P = IV)



## **Thrust Vectoring**

- 1 to 2 degree deflection needed to point thrust vector through the center of mass
- Options
  - Fixed steering coils after the magnetic nozzle
  - Gimbaled engine
  - Moving mass



Field lines as deflected by a steering coil



## **Instrumentation and Control**

- Triply redundant
- Radiation hard processors
  - BAE 5545 Multi-Core
  - For deep space environment
- Plasma measurements
- Power system measurements
- Interacts with the spacecraft control system
- Uses PPPL Central Instrumentation and Control System (CPCS) data handling system
  - Based on EPICS, Experimental Physics Industrial Control System
  - SpaceWire used for networking





## Structure

- Handles launch loads and superconducting coil loads
  - Engine and spacecraft must undergo shock and vibration testing

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- Fuel slosh is a consideration
- Delta IV
  - Launch loads are typically 5-6 g axial
  - Sinusoidal vibration
    - Thrust: 1.27 cm 5 to 6.2 Hz, 1 g 6.2 to 100 Hz
    - Lateral: 0.7 g 5 to 100 Hz
  - Acoustic
  - Shock at separation





## **Thrust Augmentation**

- H or D is used as a **propellant** it flows along the magnetic field lines outside of the separatrix; scrape-off layer (SOL) e- are heated by the fusion products that are ejected into the SOL; e- energy transferred to ions in plume expansion
- This reduces the exhaust velocity of the fusion products from 25,000 km/s to  ${\sim}50$  km/s and increases thrust to  ${>}20$  N
- Thrust/I<sub>sp</sub> is adjustable based on rate that gas is injected into the gas box
- The exhaust plume is directed by a magnetic nozzle, consisting of a throat coil and nozzle coils to accelerate the flow.





# Startup

- Fusion engine needs to be started and restarted in space
  - Initiate nuclear fusion
  - Charge the superconducting coils
  - Roughly 100 seconds of power required
- $\bullet\,$  Employs combustor burning  $D_2$  and  $O_2$  carried onboard
  - D<sub>2</sub>O can be recycled via electrolysis
    - We have power to spare



## **Fuel Storage**

- Store cryogenic deuterium and helium-3
- Super-insulated tanks and propellant lines
  - Uses Multi-layer Insulation (MLI)
- Cryocoolers to recycle vapor that is not needed for propulsion
  - Same cryocoolers used for coil cooling





NASA Zero Boil-off Experiment

## Vacuum Vessel

- Presents first wall to plasma
  - Must minimize contamination
- Supports instrumentation
- Keeps spacecraft debris and outgassing outside the fusion chamber
- Pressure differential very small



# Shielding

- Protect from neutrons and radiation
  - Superconducting coils are susceptible to neutron damage
- Bremsstrahlung and synchrotron radiation must be recycled for the RMF drive
  - Absorbed by tungsten lining the reactor cooling tubes
- Boron Carbide for neutron shielding
- Some shielding may be required for the payload and for operation in low-earth orbit near astronauts
- Want to minimize shielding
  - Reduces specific power
  - Increases radius of superconducting coils





### **Other Missions**

Mission	Cost (%B)	Flight (Years)	DFD Flight (Years)	DFD Savings (\$B)	Reference
Enceladus Orbiter	1.9	9.5	1.0	0.14	[7, 8]
Jupiter Europa Orbiter	4.7	6.0	1.0	0.10	[7, 9]
Uranus Orbiter and Probe	2.7	8.0	2.0	-0.03	[7, 10]
Venus Climate Mission	2.4	0.4	0.1	-0.32	[7, 11]
Neptune Orbiter	?	16.0	2.0	0.70	[12]
Jupiter Icy Moon Orbiter	16.3	10.0	1.0	1.57	[13]
Pluto Orbiter (REACTIONN)	2.4	5.2	4.0	0.23	[6]
Interstellar Probe Mission	?	15.0	6.8	0.18	[14]





Mars human orbital mission



## **Conclusions/Work in Progress**

- Specific power is critical
  - Thrust power to mass
  - Total electric plus thrust power to mass
- Thrust/mass determines trip time
- Mass of all subsystems needs to be quantified
- Writing a design document
  - Preliminary design level of information
  - Will allow design to critical design level in next phase

